

Introduction to G -Expectation, G -Brownian motion and G -Backward SDEs

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The aim of the talk

- *Introduction to G-stochastic analysis theory (S. Peng).*
- *Part of my work in this research field.*

1. Non linear expectations: a general framework

Setting

$$C_{l.Lip}(\mathbb{R}^n) := \{ \varphi : \mathbb{R}^n \mapsto \mathbb{R} \mid \exists C_\varphi \in \mathbb{R}^+, m \in \mathbb{N} \text{ s.t.} \\ |\varphi(x) - \varphi(y)| \leq C_\varphi (1 + |x|^m + |y|^m) |x - y| \}$$

$$Lip_b(\mathbb{R}^n) := \{ f : \mathbb{R}^n \mapsto \mathbb{R} \mid \exists M_f, C_f \in \mathbb{R}^+ \text{ s.t.} \\ |f(x)| \leq M_f, |f(x) - f(y)| \leq C_f |x - y| \}$$

Let $\Omega = \mathbb{R}$ and let \mathcal{H} be a linear space of real functions s.t.

$$X_1, \dots, X_n \in \mathcal{H} \Rightarrow \varphi(X_1, \dots, X_n) \in \mathcal{H}, \forall \varphi \in C_{l.Lip}(\mathbb{R}^n).$$

1. Non linear expectations: a general framework

Definition

A non linear expectation $\hat{\mathbb{E}}$ is a functional $\mathcal{H} \mapsto \mathbb{R}$ satisfying the following properties:

- *Monotonicity*: $X, Y \in \mathcal{H}$ and $X \geq Y \Rightarrow \hat{\mathbb{E}}[X] \geq \hat{\mathbb{E}}[Y]$.
- *Preservation of constants*: $\hat{\mathbb{E}}[c] = c, \forall c \in \mathbb{R}$.

A sub linear expectation in addition satisfies:

- *Subadditivity*: $\hat{\mathbb{E}}[X + Y] \leq \hat{\mathbb{E}}[X] + \hat{\mathbb{E}}[Y], \forall X, Y \in \mathcal{H}$.
- *Positive homogeneity*: $\hat{\mathbb{E}}[\lambda X] = \lambda \hat{\mathbb{E}}[X], \forall \lambda \geq 0, X \in \mathcal{H}$.

1. Non linear expectations: a general framework

Remark

Norm on \mathcal{H} : $\|X\| := \hat{\mathbb{E}}[|X|]$, $X \in \mathcal{H}$.

$(\mathcal{H}, \|\cdot\|)$ is a normed space.

We denote its completion by $([\mathcal{H}], \|\cdot\|)$, or simply $[\mathcal{H}]$.

2. G -Normal distributions

Let $0 \leq \sigma_1^2 \leq \sigma_2^2$, $X \in \mathcal{H}$; $G(a) = \frac{1}{2}(\sigma_2^2 a^+ - \sigma_1^2 a^-)$, $\forall a \in \mathbb{R}$.

Classical case

$$\sigma^2 = \sigma_1^2 = \sigma_2^2.$$

$X \sim \mathcal{N}(0, \sigma^2)$ can be characterized by

$u(t, x) = \mathbb{E}[\varphi(x + \sqrt{t}X)]$, for $\varphi \in C_{l.Lip}(\mathbb{R})$, which satisfies

$$\partial_t u(t, x) = \frac{1}{2} \sigma^2 \partial_{xx}^2 u(t, x), \quad u(0, x) = \varphi(x).$$

G-case (Definition)

$X \sim \mathcal{N}(0, [\sigma_1^2, \sigma_2^2])$ is characterized by

$u(t, x) = \hat{\mathbb{E}}[\varphi(x + \sqrt{t}X)]$, for $\varphi \in C_{l.Lip}(\mathbb{R})$,
which is the unique viscosity solution of

$$\partial_t u - G(\partial_{xx}^2 u) = 0, \quad u(0, x) = \varphi(x).$$

2. G -Normal distributions

Proposition

If $X \sim \mathcal{N}(0, [\sigma_1^2, \sigma_2^2])$, we have the following property:

- For each **convex** $\varphi \in C_{l.Lip}(\mathbb{R})$,

$$u(t, x) = \hat{\mathbb{E}}[\varphi(x + \sqrt{t}X)] = \frac{1}{2\sqrt{\pi t}\sigma_2} \int_{-\infty}^{\infty} e^{-\frac{x^2}{2\sigma_2^2 t}} \varphi(x) dx;$$

- For each **concave** $\varphi \in C_{l.Lip}(\mathbb{R})$, for $\sigma_1 > 0$,

$$u(t, x) = \hat{\mathbb{E}}[\varphi(x + \sqrt{t}X)] = \frac{1}{2\sqrt{\pi t}\sigma_1} \int_{-\infty}^{\infty} e^{-\frac{x^2}{2\sigma_1^2 t}} \varphi(x) dx.$$

2. G -Normal distributions

Definition

A random vector $Y = (Y_1, \dots, Y_n)$, $Y_i \in \mathcal{H}$, is said to be *independent* of $X = (X_1, \dots, X_m)$, $X_i \in \mathcal{H}$, if for each $\varphi \in C_{l.Lip}(\mathbb{R}^m \times \mathbb{R}^n)$,

$$\hat{\mathbb{E}}[\varphi(X, Y)] = \hat{\mathbb{E}}[\hat{\mathbb{E}}[\varphi(x, Y)]_{x=X}].$$

2. G -Normal distributions

Remark

Unlike the classical case, the independence under $\hat{\mathbb{E}}$ is not symmetric.

Example

Let $X, Y \in \mathcal{H}$ be s.t. $\sigma_2^2 := \hat{\mathbb{E}}[Y^2] > \sigma_1^2 := -\hat{\mathbb{E}}[-Y^2] > 0$, $\hat{\mathbb{E}}[X] = \hat{\mathbb{E}}[-X] = 0$, and $\hat{\mathbb{E}}[|X|] > 0$. Then if Y is independent of X :

$$\begin{aligned}\hat{\mathbb{E}}[XY^2] &= \hat{\mathbb{E}}[\hat{\mathbb{E}}[xY^2]_{x=X}] = \hat{\mathbb{E}}[(x^+ \hat{\mathbb{E}}[Y^2] + x^- \hat{\mathbb{E}}[-Y^2])_{x=X}] \\ &= \hat{\mathbb{E}}[X^+ \sigma_2^2 - X^- \sigma_1^2] = \hat{\mathbb{E}}[X^+] (\sigma_2^2 - \sigma_1^2) > 0.\end{aligned}$$

But if X is independent of Y :

$$\hat{\mathbb{E}}[XY^2] = \hat{\mathbb{E}}[\hat{\mathbb{E}}[Xy^2]_{y=Y}] = \hat{\mathbb{E}}[(y^2 \hat{\mathbb{E}}[X])_{y=Y}] = \hat{\mathbb{E}}[\hat{\mathbb{E}}[X] Y^2] = 0.$$

2. G -Normal distributions

Definition

X, Y are said to be *identically distributed* ($X \sim Y$, or X is a copy of Y), if $\hat{\mathbb{E}}[\varphi(X)] = \hat{\mathbb{E}}[\varphi(Y)], \forall \varphi \in C_{l.Lip}(\mathbb{R})$.

Definition

A sequence $\{\eta_i\}_{i=1}^\infty$ in \mathcal{H} is said to *converge in law* to $\eta \in \mathcal{H}$ under $\hat{\mathbb{E}}$ if

$$\lim_{i \rightarrow \infty} \hat{\mathbb{E}}[\varphi(\eta_i)] = \hat{\mathbb{E}}[\varphi(\eta)],$$

for each $\varphi \in Lip_b(\mathbb{R})$.

2. G -Normal distributions

Central Limit Theorem (Peng)

Let $\{X_i\}_{i=1}^\infty$ in $(\Omega, \mathcal{H}, \hat{\mathbb{E}})$ satisfy $X_i \sim X_1$, each X_{i+1} is independent of (X_1, \dots, X_i) ,

$$\hat{\mathbb{E}}[|X_1|^{2+\alpha}] < \infty, \text{ for some } \alpha > 0, \text{ and } \hat{\mathbb{E}}[X_1] = \hat{\mathbb{E}}[-X_1] = 0.$$

$S_n := X_1 + \dots + X_n$. Then S_n/\sqrt{n} converges in law to $\mathcal{N}(0; [\sigma_1^2, \sigma_2^2])$:

$$\lim_{n \rightarrow \infty} \hat{\mathbb{E}}[\varphi(S_n/\sqrt{n})] = \hat{\mathbb{E}}[\varphi(X)], \forall \varphi \in Lip_b(\mathbb{R}),$$

where $X \sim \mathcal{N}(0, [\sigma_1^2, \sigma_2^2])$, $\sigma_1^2 = -\hat{\mathbb{E}}[-X_1^2]$, $\sigma_2^2 = \hat{\mathbb{E}}[X_1^2]$.

3. G -Brownian motion under G -expectation

Setting

Let $\Omega = C_0(\mathbb{R}^+)$ the space of continuous paths $(\omega_t)_{t \in \mathbb{R}^+}$ with $\omega_0 = 0$; distance on Ω :

$$\rho(\omega^1, \omega^2) := \sum_{i=1}^{\infty} 2^{-i} [(\max_{t \in [0, i]} |\omega_t^1 - \omega_t^2|) \wedge 1].$$

Coordinate process on Ω : $B_t(\omega) = \omega_t$, $t \geq 0$, $\omega \in \Omega$.

For $t \in [0, +\infty)$, we set

$$\mathcal{H}_t := \{ \varphi(\omega_{t_1}, \dots, \omega_{t_n}) : \forall n \in \mathbb{N}, t_1, \dots, t_n \in [0, t], \\ \forall \varphi \in C_{l.Lip}(\mathbb{R}^n) \};$$

$$\mathcal{H} := \bigcup_{n=1}^{\infty} \mathcal{H}_n.$$

3. G -Brownian motion under G -expectation

Definition

The coordinate process B on $(\Omega, \mathcal{H}, \hat{\mathbb{E}})$ is a *G -Brownian motion* if:

- 1 $B_0 = 0$;
- 2 $B_{t+s} - B_t$ is $\mathcal{N}(0; [\sigma_1^2 s, \sigma_2^2 s])$ - distributed, $\forall t, s \geq 0$;
- 3 For each $n \geq 2$, $0 \leq t_1 \leq \dots \leq t_n$, $B_{t_n} - B_{t_{n-1}}$ is independent of $(B_{t_1}, B_{t_2}, \dots, B_{t_n})$.

3. G -Brownian motion under G -expectation

Theorem (Peng)

Let $B_t(\omega)_{t \geq 0}$ be a process on $(\Omega, \mathcal{H}, \hat{\mathbb{E}})$ such that

- 1 For each $0 \leq t_1 \leq \dots \leq t_n$, $B_{t_n} - B_{t_{n-1}}$ is independent of $(B_{t_1}, B_{t_2}, \dots, B_{t_{n-1}})$;
- 2 B_t has the same distribution as $B_{t+s} - B_s$, $\forall t, s \geq 0$;
- 3 $\lim_{t \downarrow 0} \hat{\mathbb{E}}[|B_t|^3]t^{-1} = 0$,

then B is a G -Brownian motion, for

$$\sigma_1^2 = -\hat{\mathbb{E}}[-B_1^2], \quad \sigma_2^2 = \hat{\mathbb{E}}[B_1^2].$$

For what follows: for simplicity, we choose $\sigma_2^2 = 1$.

3. G -Brownian motion under G -expectation

Definition

The related *conditional expectation* of $X = \varphi(B_{t_1}, B_{t_2} - B_{t_1}, \dots, B_{t_m} - B_{t_{m-1}})$ under \mathcal{H}_{t_j} is defined by

$$\hat{\mathbb{E}}[X | \mathcal{H}_{t_j}] = \psi(B_{t_1}, B_{t_2} - B_{t_1}, \dots, B_{t_j} - B_{t_{j-1}}),$$

where $\psi(x_1, \dots, x_j) = \hat{\mathbb{E}}[\varphi(x_1, \dots, x_j, B_{t_{j+1}} - B_{t_j}, \dots, B_{t_m} - B_{t_{m-1}})]$.

Definition

A process $(M_t)_{t \geq 0}$ is called a *G -martingale (resp. G -submartingale, G -supermartingale)*, if $\forall t \in [0, +\infty)$, $M_t \in \mathcal{H}_t$ and for $s \in [0, t]$,

$$\hat{\mathbb{E}}[M_t | \mathcal{H}_s] = M_s \text{ (resp. } \leq M_s, \geq M_s) \text{ a.s. in } \mathcal{H}.$$

4. Itô's integral of G -Brownian motion

Setting

$$L_G^2(\mathcal{H}_t) := \{\xi \in \mathcal{H}_t : \hat{\mathbb{E}}[|\xi|^2] < \infty\}.$$

$$L_G^{2,0}(0, T) := \{\eta(\omega) \mid \eta_t(\omega) = \sum_{j=0}^{N-1} \xi_j(\omega) I_{[t_j, t_{j+1})}(t),$$

$$\text{where } \xi_j \in L_G^2(\mathcal{H}_{t_j}), 0 = t_0 < t_1 < \dots < t_N = T\}.$$

Definition

For each $(\eta_t)_{0 \leq t \leq T} \in L_G^{2,0}(0, T)$, we define its Itô's integral as

$$I(\eta) = \int_0^T \eta(s) dB_s := \sum_{j=0}^{N-1} \xi_j (B_{t_{j+1}} - B_{t_j}).$$

4. Itô's integral of G -Brownian motion

Lemma

We have

$$\hat{\mathbb{E}}\left[\int_0^T \eta(s) dB_s\right] = 0,$$

and

$$\hat{\mathbb{E}}\left[\left(\int_0^T \eta(s) dB_s\right)^2\right] \leq \int_0^T \hat{\mathbb{E}}[(\eta_s)^2] ds.$$

We denote by $L_G^2(0, T)$ the completion of $L_G^{2,0}(0, T)$ under the norm

$$\|\eta\|_{L_G^2(0, T)} = \left\{ \int_0^T \hat{\mathbb{E}}[|\eta_t|^2] dt \right\}^{1/2}.$$

Hence the stochastic integral can be extended to $L_G^2(0, T)$.

4. Itô's integral of G -Brownian motion

We denote: $\langle B \rangle_t = B_t^2 - 2 \int_0^t B_s dB_s$, then

$$\hat{\mathbb{E}}[|\langle B \rangle_t - \sum_{k=0}^{N-1} (B_{t_{k+1}} - B_{t_k})^2|^2] \rightarrow 0, N \rightarrow +\infty.$$

$\langle B \rangle$ is an increasing process; it is called *the quadratic variation of B* .

Proposition

$$\hat{\mathbb{E}}[\langle B \rangle_t] = t, \text{ but } \hat{\mathbb{E}}[-\langle B \rangle_t] = -\sigma_1^2 t.$$

$$\hat{\mathbb{E}}[(\int_0^T h(s) dB_s)^2] = \hat{\mathbb{E}}[\int_0^T h^2(s) d\langle B \rangle_s], h \in L_G^2(0, T).$$

4. Itô's integral of G -Brownian motion

Consider

$$X_t = X_0 + \int_0^t \alpha_s ds + \int_0^t \eta_s d\langle B \rangle_s + \int_0^t \beta_s dB_s.$$

Itô's formula (Peng)

Let α, β, η be bounded processes of $L_G^2(0, T)$. Then for each $t \geq s \geq 0$ and $\Phi(X_t) \in L_G^2(\mathcal{H}_t)$, we have

$$\begin{aligned} \Phi(X_t) = \Phi(X_s) &+ \int_s^t \Phi_x(X_u) \beta_u dB_u + \int_s^t \Phi_x(X_u) \alpha_u du \\ &+ \int_s^t [\Phi_x(X_u) \eta_u + \frac{1}{2} \Phi_{xx}(X_u) \beta_u^2] d\langle B \rangle_u. \end{aligned}$$

5. SDE and BSDE driven by a G -Brownian motion

Now we can consider the following G -SDE:

$$X_t = X_0 + \int_0^t b(X_s) ds + \int_0^t h(X_s) d\langle B \rangle_s + \int_0^t \sigma(X_s) dB_s, t > 0.$$

where $X_0 \in \mathbb{R}$, $b, h, \sigma : \mathbb{R} \rightarrow \mathbb{R}$ are Lipschitz functions.

Theorem (Peng)

There exists a unique solution $X \in L_G^2(0, T)$ of the above G -SDE.

5. SDE and BSDE driven by a G -Brownian motion

Recall

Classical BSDE (under a linear expectation):

$$\begin{cases} dY_t = -f(t, Y_t, Z_t)dt + Z_t dB_t, \\ Y_T = \xi \in L^2(\Omega, \mathcal{F}_T, P); \end{cases}$$

solution $(Y_t, Z_t)_{0 \leq t \leq T}$; existence and uniqueness for f Lipschitz in (y, z) and linear growth. For $f \equiv 0$: the martingale representation theorem.

Remark

No martingale representation theorem in G -theory up to now!

5. SDE and BSDE driven by a G -Brownian motion

Unlike the classical case, we only consider the G -BSDE of the following type:

$$Y_t = \hat{\mathbb{E}}[\xi + \int_t^T f(s, Y_s) ds | \mathcal{H}_t], \quad t \in [0, T],$$

where $\xi \in L_G^2(\mathcal{H}_T)$. $f(t, y) \in L_G^2(0, T)$, $y \in \mathbb{R}$, is a given Lipschitz function with respect to y .

Theorem (Peng)

There exists a unique solution $(Y_t)_{t \in [0, T]} \in L_G^2(0, T)$.

5. SDE and BSDE driven by a G -Brownian motion

$$Y_t^i = \hat{\mathbb{E}}[\xi^i + \int_t^T f_i(s, Y_s^i) ds | \mathcal{H}_t], \quad t \in [0, T],$$

where $\xi^i \in L_G^2(\mathcal{H}_T)$, $f_i(t, y) \in L_G^2(0, T)$, $y \in \mathbb{R}$, for $i = 1, 2$.

Comparison Theorem (Jing)

Suppose that $\xi^1 \geq \xi^2$, $f_1(t, y) \geq f_2(t, y)$, $\forall (t, y)$, $f_1 \uparrow$ or $f_2 \downarrow$ in y , both f_1 and f_2 are Lipschitz in y and bounded, then $Y_t^1 \geq Y_t^2$, $\forall t \in [0, T]$.

6.A property of G -martingales

Proposition

Let $x \in \mathbb{R}$, $Z \in L_G^2(0, T)$, and $\eta \in L_G^2(0, T)$, then the process

$$M_t = x + \int_0^t Z_s dB_s + \int_0^t \eta_s d\langle B \rangle_s - \int_0^t 2G(\eta_s) ds$$

is a G -martingale.

Recall

If $\sigma_1 = 1$, $\int_0^t \eta_s d\langle B \rangle_s - \int_0^t 2G(\eta_s) ds = 0$.

Question

Is the stochastic integral w. r. t. this G -martingale still a G -martingale?

6.A property of G -martingales

Remark

$\{M_t\}$ being a G -martingale does not always imply that $\{-M_t\}$ is a G -martingale.

Example

$\{B_t\}$ and $\{-B_t\}$ are both G -martingales.
 $\{\langle B \rangle_t - t\}$ is a G -martingale, but $\{-\langle B \rangle_t + t\}$ is not a G -martingale.

6.A property of G -martingales

Theorem (Jing)

Let $0 \leq \sigma_1 < 1$ and $\xi \in L_G^2(0, T)$. Put

$$M_t = x + \int_0^t Z_s dB_s + \int_0^t \eta_s d\langle B \rangle_s - \int_0^t 2G(\eta_s) ds,$$

and

$$N_t = \int_0^t \xi_s dM_s, \quad t \geq 0.$$

Then $\{N_t\}$ is a G -martingale w. r. t. $\{\mathcal{H}_t\}$ if and only if

$$\begin{cases} \operatorname{sgn}(\xi_s) \geq 0, & \text{on } \{s : \eta_s \neq 0\}; \\ \operatorname{sgn}(\xi_s) \text{ can be arbitrary,} & \text{on } \{s : \eta_s = 0\}. \end{cases}$$

This talk is mainly based on

- Peng, S. (2006) *G-Expectation, G-Brownian Motion and Related Stochastic Calculus of Itô's type*, Proceedings of 2005 Abel Symposium, Springer
- Peng, S. (2008) *Multi-Dimensional G-Brownian Motion and Related Stochastic Calculus under G-Expectation*, Stochastic Processes and their Applications, Vol. 118, Issue 12, Dec. 2008, 2223-2253
- Peng, S. (2008) *A New Central Limit Theorem under Sublinear Expectations*, arXiv:0803.2656v1 [math.PR] 18 Mar 2008

Thank you!

谢谢!