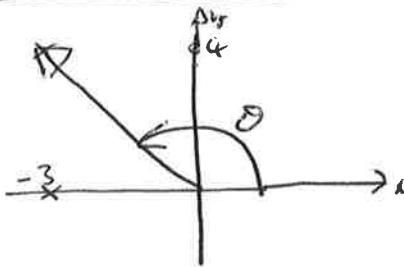


# Solutions aux exercices (révision) § 3-4.

①

I.  $x = -3, y = 4$



$$r = \sqrt{x^2 + y^2} = \sqrt{9 + 16} = 5$$

$$\theta = \arctan \frac{y}{x} = \arctan \left( -\frac{4}{3} \right)$$

Alors  $\arctan \frac{4}{3} \approx 53^\circ$ , d'où  $\arctan \left( -\frac{4}{3} \right) \approx 180^\circ - 53^\circ = 127^\circ$

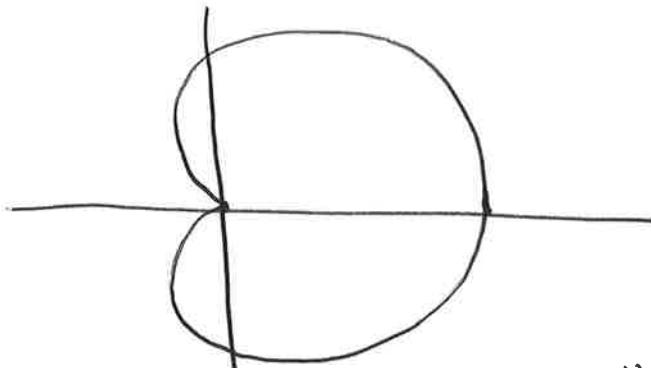
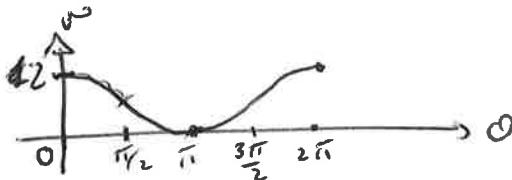
II  $r = \sqrt{x^2 + y^2 + z^2}, \lambda = \arctan \frac{y}{x}, \delta = \arccos \left( \frac{z}{\sqrt{x^2 + y^2 + z^2}} \right)$

On a besoin d'une calculatrice - il faut faire attention au quadrant du point, car  $x, y, z$  sont tous négatifs, d'où

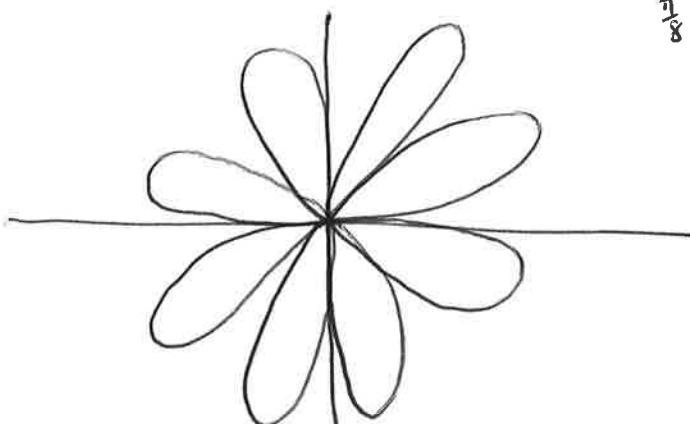
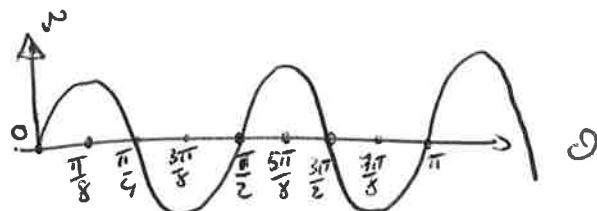
$$\pi < \lambda < \frac{3\pi}{2}. \text{ En effet } \lambda = \arctan \frac{y}{x} = \arctan \frac{247804}{245622}$$

qu'on calcule, qui va donner quelque chose entre 0 et  $\pi/2$ , puis on ajoute  $\pi$ .

III  $r = 1 + \cos \theta$

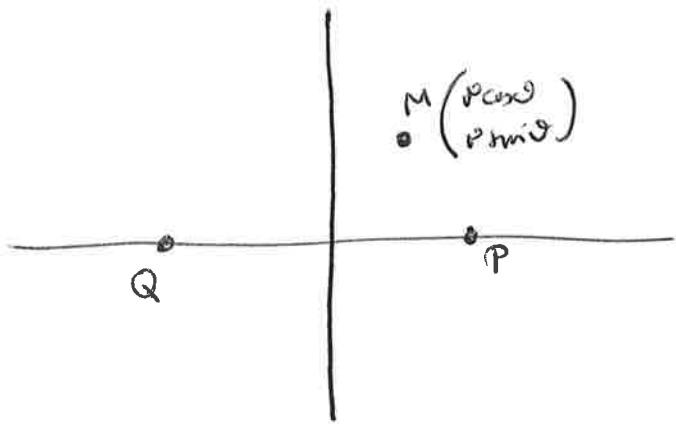


IV Faire au classe



(2)

V.



$$MP = \sqrt{(1 - r \cos \theta)^2 + r^2 \sin^2 \theta} = \sqrt{1 - 2r \cos \theta + r^2 \cos^2 \theta + r^2 \sin^2 \theta} = \sqrt{1 + r^2 - 2r \cos \theta}$$

$$MQ = \sqrt{(1 + r \cos \theta)^2 + r^2 \sin^2 \theta} = \sqrt{1 + r^2 + 2r \cos \theta}$$

$$MP \times MQ = 1 \Leftrightarrow \sqrt{1 + r^2 - 2r \cos \theta} \sqrt{1 + r^2 + 2r \cos \theta} = 1$$

$$\Leftrightarrow \sqrt{(1 + r^2 - 2r \cos \theta)(1 + r^2 + 2r \cos \theta)} = 1$$

$$\Leftrightarrow \sqrt{(1 + r^2)^2 - 4r^2 \cos^2 \theta} = 1$$

$$\Leftrightarrow \sqrt{r^4 + 2r^2 - 4r^2 \cos^2 \theta + 1} = 1$$

$$\text{On note que } 1 - 2\cos^2 \theta = -\cos 2\theta$$

On prend le carré de chaque partie :

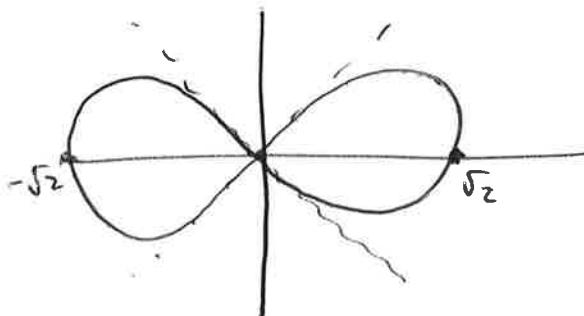
$$r^4 + 1 - 2r^2 \cos 2\theta = 1$$

$$\Leftrightarrow r^4 - 2r^2 \cos 2\theta = 0 \Leftrightarrow r^2 = 2 \cos 2\theta$$

Il faut alors que  $\cos 2\theta \geq 0$  c'est à dire  $-\frac{\pi}{2} \leq 2\theta \leq \frac{\pi}{2}$

$$\Leftrightarrow -\frac{\pi}{4} \leq \theta \leq \frac{\pi}{4}$$

Pour chaque  $\theta$  entre  $-\frac{\pi}{4}$  et  $\frac{\pi}{4}$  il y a deux valeurs de  $r = \sqrt{2 \cos 2\theta}$



VII (a) Coord cylindriques:  $x = r \cos \theta$ ,  $y = r \sin \theta$ ,  $z = z$

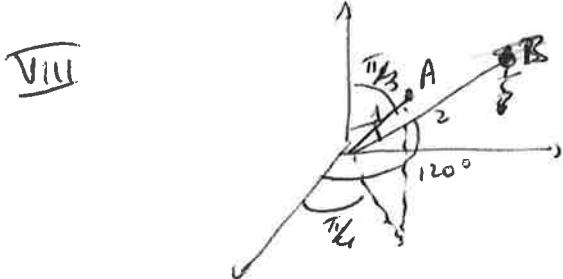
$$\begin{aligned}
 d_{AB} &= \sqrt{(x_A - x_B)^2 + (y_A - y_B)^2 + (z_A - z_B)^2} = \sqrt{(\rho_A \cos \vartheta_A - \rho_B \cos \vartheta_B)^2 + (\rho_A \sin \vartheta_A - \rho_B \sin \vartheta_B)^2 + (z_A - z_B)^2} \\
 &= \sqrt{\left\{ \rho_A^2 \cos^2 \vartheta_A - 2 \rho_A \rho_B \cos \vartheta_A \cos \vartheta_B + \rho_B^2 \cos^2 \vartheta_B + \rho_A^2 \sin^2 \vartheta_A - 2 \rho_A \rho_B \sin \vartheta_A \sin \vartheta_B \right.} \\
 &\quad \left. + \rho_B^2 \sin^2 \vartheta_B + (z_A - z_B)^2 \right\}} \\
 &= \sqrt{\left\{ \rho_A^2 + \rho_B^2 - 2 \rho_A \rho_B (\cos \vartheta_A \cos \vartheta_B + \sin \vartheta_A \sin \vartheta_B) + (z_A - z_B)^2 \right\}} \\
 &= \sqrt{\rho_A^2 + \rho_B^2 - 2 \rho_A \rho_B \cos(\vartheta_A - \vartheta_B) + (z_A - z_B)^2}
 \end{aligned}$$

(b) similaire.

VIII.  $(\rho_A, \vartheta_A, \lambda_A) = (1, \frac{\pi}{2}, \pi)$ ,  $(\rho_B, \vartheta_B, \lambda_B) = (8, \frac{\pi}{4}, 5\sqrt{2})$

$$\begin{array}{l|l}
 \begin{array}{l}
 x = r \sin \vartheta \cos \lambda \\
 y = r \sin \vartheta \sin \lambda \\
 z = r \cos \vartheta
 \end{array} &
 \begin{array}{ll}
 \lambda_A = \frac{1}{2} \sin \frac{\pi}{2} \cos \pi = 1 \times 1 \times (-1) = -1 \\
 y = 1 \sin \frac{\pi}{2} \sin \pi = 1 \times 1 \times 0 = 0 \\
 z = 1 \cos \frac{\pi}{2} = 1 \times 0 = 0
 \end{array}
 \end{array}$$

$$\begin{array}{lll}
 x_B = 8 \sin \frac{\pi}{4} \cos \frac{5\pi}{4} & = 8 \times \frac{1}{\sqrt{2}} \times \left(-\frac{1}{\sqrt{2}}\right) & = -4 \\
 y_B = 8 \sin \frac{\pi}{4} \sin \frac{5\pi}{4} & = 8 \times \frac{1}{\sqrt{2}} \times \left(-\frac{1}{\sqrt{2}}\right) & = -4 \\
 z_B = 8 \cos \frac{\pi}{4} & = 8 \times \frac{1}{\sqrt{2}} & = \frac{8}{\sqrt{2}}
 \end{array}
 \quad \left( \begin{array}{l}
 \cos \frac{5\pi}{4} = \cos(\pi + \frac{\pi}{4}) \\
 = -\cos \frac{\pi}{4} = -\frac{1}{\sqrt{2}} \cos \frac{\pi}{4} \\
 = -1 \times \frac{1}{\sqrt{2}}
 \end{array} \right)$$



Soir  $\alpha$  l'angle  $AOB$

$$\text{Alors } \cos \alpha = \frac{\overrightarrow{OA} \cdot \overrightarrow{OB}}{\|\overrightarrow{OA}\| \|\overrightarrow{OB}\|}$$

On remarque que  $\|\overrightarrow{OA}\| = \rho_A$ ,  $\|\overrightarrow{OB}\| = \rho_B$

$$\text{d'où } \frac{\overrightarrow{OA}}{\|\overrightarrow{OA}\|} = \frac{1}{\rho_A} (\rho_A \sin \vartheta_A \cos \lambda_A, \rho_A \sin \vartheta_A \sin \lambda_A, \rho_A \cos \vartheta_A) = (\sin \vartheta_A \cos \lambda_A, \sin \vartheta_A \sin \lambda_A, \cos \vartheta_A)$$

$$\begin{aligned}
 \cos \alpha &= \left( \sin \frac{\pi}{3} \cos \frac{\pi}{4}, \sin \frac{\pi}{3} \sin \frac{\pi}{4} \cos \frac{\pi}{3} \right) \circ \left( \sin \frac{\pi}{2} \cos \frac{2\pi}{3}, \sin \frac{\pi}{2} \sin \frac{2\pi}{3}, \cos \frac{\pi}{2} \right) \\
 &= \left( \frac{\sqrt{3}}{2} \frac{1}{\sqrt{2}}, \frac{1}{2} \frac{1}{\sqrt{2}}, \frac{1}{2} \right) \circ \left( 1 \left(-\frac{1}{2}\right), 1 \times \frac{\sqrt{3}}{2}, 0 \right) = -\frac{\sqrt{3}}{4\sqrt{2}} + \frac{3}{4\sqrt{2}} = \frac{3-\sqrt{3}}{4\sqrt{2}}
 \end{aligned}$$

$$\alpha = \arccos \left( \frac{3-\sqrt{3}}{4\sqrt{2}} \right)$$

## § 4.6

I et II Voir solution à la question 4 de l'épreuve d'entraînement.

$$\text{III } AB = \begin{pmatrix} 1 & -1 & 0 \\ 2 & 0 & 1 \\ -3 & -1 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 & 3 \\ 1 & -1 & 0 \\ 1 & 1 & 2 \end{pmatrix} = \begin{pmatrix} 0-1+0 & 1+1+0 & 3-0+0 \\ 0+0+1 & 2+0+1 & 6+0+2 \\ 0-1+1 & -3+1+1 & -9+0+2 \end{pmatrix} = \begin{pmatrix} -1 & 2 & 3 \\ 1 & 3 & 8 \\ 0 & -1 & -7 \end{pmatrix}$$

$$BA = \begin{pmatrix} 0 & 1 & 3 \\ 1 & -1 & 0 \\ 1 & 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & -1 & 0 \\ 2 & 0 & 1 \\ -3 & -1 & 1 \end{pmatrix} = \begin{pmatrix} 0+2-9 & 0+0-3 & 0+1+3 \\ 1-2+0 & -1+0+0 & 0-1+0 \\ 1+2-6 & -1+0-2 & 0+1+2 \end{pmatrix} = \begin{pmatrix} -7 & -3 & 4 \\ -1 & -1 & -1 \\ -3 & -3 & 3 \end{pmatrix}$$

$$AB - BA = \begin{pmatrix} -1 & 2 & 3 \\ 1 & 3 & 8 \\ 0 & -1 & -7 \end{pmatrix} - \begin{pmatrix} -7 & -3 & 4 \\ -1 & -1 & -1 \\ -3 & -3 & 3 \end{pmatrix} = \begin{pmatrix} 6 & 5 & -1 \\ 2 & 4 & 9 \\ 3 & 2 & -10 \end{pmatrix}$$

$\text{trace}(AB - BA) = 6 + 4 - 10 = 0$ , ce qui démontre que  $\text{trace } AB = \text{trace } BA$   
(même si  $AB \neq BA$ )

$$\text{IV } A = \begin{pmatrix} 3 & -1 & 1 \\ 1 & 5 & -1 \\ 5 & 1 & 1 \end{pmatrix}; \det A = \det \begin{pmatrix} -2 & 0 & 0 \\ 1 & -1 & 0 \\ 5 & 1 & 1 \end{pmatrix} \quad (\text{ligne 1 - ligne 3})$$

$$= -2 \begin{vmatrix} 1 & 0 \\ 1 & 1 \end{vmatrix} = -2 \times (-1) = 2$$

$$\text{can}(A) = \begin{pmatrix} \begin{vmatrix} 1 & 0 \\ 1 & 1 \end{vmatrix} & -\begin{vmatrix} 1 & 0 \\ 5 & 1 \end{vmatrix} & \begin{vmatrix} 1 & -1 \\ 5 & 1 \end{vmatrix} \\ -\begin{vmatrix} 1 & 1 \\ 1 & 1 \end{vmatrix} & \begin{vmatrix} 3 & 1 \\ 5 & 1 \end{vmatrix} & -\begin{vmatrix} 3 & 1 \\ 5 & 1 \end{vmatrix} \\ \begin{vmatrix} 1 & 0 \\ 1 & 0 \end{vmatrix} & -\begin{vmatrix} 3 & 1 \\ 1 & 0 \end{vmatrix} & \begin{vmatrix} 3 & 1 \\ 1 & -1 \end{vmatrix} \end{pmatrix} = \begin{pmatrix} -1-0 & -(1-0) & 1+5 \\ -(1-1) & 3-5 & 3-5 \\ 0+1 & -(0-1) & -3-1 \end{pmatrix} = \begin{pmatrix} -1 & -1 & 6 \\ 0 & -2 & 2 \\ 1 & 1 & -4 \end{pmatrix}$$

$$A^{-1} = \frac{1}{\det A} \text{can}(A) = \frac{1}{2} \begin{pmatrix} -1 & 0 & 1 \\ -1 & -2 & 1 \\ 6 & 2 & -4 \end{pmatrix}$$

Les équations de la question IV s'écrivent  $A \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 2 \end{pmatrix}$

$$\text{d'où } \begin{pmatrix} x \\ y \\ z \end{pmatrix} = A^{-1} \begin{pmatrix} 1 \\ 1 \\ 2 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} -1 & 0 & 1 \\ -1 & -2 & 1 \\ 6 & 2 & -4 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \\ 2 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} -1+0+2 \\ -1+2+2 \\ 6+2-8 \end{pmatrix}$$

$$= \frac{1}{2} \begin{pmatrix} 1 \\ 3 \\ -2 \end{pmatrix} = \begin{pmatrix} 1/2 \\ 3/2 \\ -1 \end{pmatrix}$$

on vérifie: equ1:  $3 \times \frac{1}{2} + \frac{3}{2} - 2 = 3 - 2 = 1 \text{ OK}$

$$\text{equ2: } x - y = \frac{1}{2} - \frac{3}{2} = -1 \text{ OK}$$

$$\text{equ3: } \frac{5}{2} + \frac{3}{2} - 2 = 4 - 2 = 2 \text{ OK.}$$